### TOTAL SOLUTION PROVIDER FOR SMART FACTORY



SMART PROGRESSION · SMART PERFORMANCE · SMART PROFESSION













## **About us**

SP SYSTEMS designs, manufactures, and supplies industrial gantry robots and factory automation systems tailored to customer requirements. In automobiles, 2nd batteries, construction, shipbuilding, and defense industries among others, the company develops and provides customized solutions based on the characteristics of each industrial sector.

In particular, SP SYSTEMS secures orders for logistics automation systems that operate 24/7, offering turnkey solutions encompassing design, installation, and commissioning. This capability has enabled the company to build strong customer trust by consistently delivering optimized systems in the shortest possible timeframe.

SP SYSTEMS will continue to uphold its management philosophy of prioritizing customer satisfaction, based on the SP spirit of 'Smart Progression', 'Smart Performance', and 'Smart Profession'.





| 1988. 05 | Established in Busan, Republic of Korea   |
|----------|---|
| 1988. 06 | Technical agreement with CIMCORP  |
| 1995. 10 | New headquarters and research institute construction (Busan)  |
| 1997. 05 | Gantry robot linear movement module development   |
| 1997. 08 | CE Mark certification (Auto Banding System),  |
|          | Establishment of a corporate-affiliated research institute  |
| 1999. 09 | Partnership agreement with ABB  |
| 2000. 11 | Quality management system certification (ISO 9001 / KS A 9001)  |
| 2001. 01 | Certified as a venture company  |
| 2001. 12 | Opened a new factory in Yangsan   |
| 2002. 08 | Designated as an INNO-BIZ (technology-innovative SME) by the Ministry of SMEs and Startups                      |
| 2005. 03 | ERP(Enterprise Resource Planning) Implementation  |
| 2005. 07 | Selected as a government-funded research institute for robot R&D projects                                       |
| 2009. 03 | Developed medium-duty linear guide systems and constructed equipment for mass production                        |
| 2010. 05 | Selected as a KOTRA Guaranteed Brand company,   |
|          | CE Mark certification (multi-axis linear module)  |
| 2013. 01 | Selected as a Global Small Giant company by the Ministry of SMEs and Startups                                   |
| 2013. 05 | Acquired KCS (Korea Certification for Safety)   |
| 2014. 12 | Established a local subsidiary in China (SP Qingdao)  |
| 2015. 11 | Constructed a second factory in Yangsan, Gyeongsangnam-do   |
| 2016. 04 | Designated as an INNO-BIZ (technology-innovative SME) by the Ministry of SMEs and Startups                      |
| 2016. 12 | Designated as an incubated company by the Gyeongnam Center for Creative Economy & Innovation                    |
| 2017. 01 | Opened Seoul office   |
| 2018. 01 | Designated as an Excellent Employment Company by Gyeongsangnam-do,  |
|          | Designated as Hyundai Motor Group's "Partner of the Year"   |
| 2019. 08 | Listed on the KOSDAQ  |
| 2020. 01 | Designated as Youth-friendly Small Giant Company  |
| 2020. 05 | Designated as 'Global Small Giant Company' by the Ministry of SMEs and Startups                                 |
|          | Signed a dealership agreement with 'Doosan Robotics'  |
| 2021. 05 | Secured the majority shares of MICUBE Solutions Co., Ltd.   |
| 2021. 12 | Environmental management system certification (ISO 14001),  |
|          | Selected as one of the "National Representative 1000 Innovative Companies" by the Ministry of SMEs and Startups |
| 2023. 08 | MICUBE Solution Co., Ltd. listed on the KOSDAQ  |
| 2024. 04 | Designated as 'Global Small Giant Company +1 000'   |

by the Ministry of SMEs and Startups

Туре

**UL-1** 

**UL-2** 

UL - 3

## **Gantry Robot** Standard Type

## 1-Axis Gantry Robot (UL-TYPE)

> A single-axis gantry robot utilizing a 1-axis linear module, capable of transporting loads of up to 400 kgf.







## 2-Axis Gantry Robot (TL-TYPE)

> A double-axis gantry robot utilizing a multi-axis linear module for linear movement in dual axes (Horizontal: X / Vertical: Z), capable of transporting loads up to 300 kgf.

Maximum Effective Payload [kgf]

300

300

| Type   | 30 | 40 | 60 | 100 | 120 | 150 | 200 | 300 |
|--------|----|----|----|-----|-----|-----|-----|-----|
| TL - E |    | 30 |    |     |     |     |     |     |
| TL - 1 |    |    |    | 60  |     |     |     |     |
| TL - 2 |    |    |    |     |     |     | 150 |     |
| TL - 3 |    |    |    |     |     |     |     |     |
|        |    |    |    |     |     |     |     |     |



## 3-Axis Gantry Robot (CL-TYPE)

> A triple-axis gantry robot utilizing a multi-axis linear module for 3D movement along three axes (Horizontal: X, Y / Vertical: Z), capable of transporting loads up to 300 kgf. Maximum Effective Payload [kgf]

| Type   | 20 | 40 | 60 | 100 | 120 | 150 | 200 | 300 |
|--------|----|----|----|-----|-----|-----|-----|-----|
| CL - 1 |    |    |    | 60  |     |     |     |     |
| CL - 2 |    |    |    |     |     | 150 |     |     |
| CL - 3 |    |    |    |     |     |     |     |     |





| Motor Chood          | Unit             | UL - 1 | UL - 2 | UL - 3 |  |  |
|----------------------|------------------|--------|--------|--------|--|--|
| Motor Speed          | Offic            | X axis | X axis | X axis |  |  |
| Max Nominal Speed    | m/s              | 2.6    | 3      | 3.3    |  |  |
| Max Acceleration     | m/s <sup>2</sup> | 3      | 4.5    | 4.5    |  |  |
| Gearbox Ratio        | _                | 3:1    | 3:1    | 3:1    |  |  |
| Motor Speed          | rpm              | 4,500  | 3,000  | 3,000  |  |  |
| Repeatable Precision | mm               |        |        | ±0.05  |  |  |

| Classification       | Unit | TL - E |       | TL    | - 1   | TL    | - 2   | TL - 3 |       |
|----------------------|------|--------|-------|-------|-------|-------|-------|--------|-------|
| Classification       |      | Xaxis  | Zaxis | Xaxis | Zaxis | Xaxis | Zaxis | Xaxis  | Zaxis |
| Max Nominal Speed    | m/s  | 3      | 2.5   | 2.6   | 2.6   | 3     | 3     | 3.3    | 3.3   |
| Max Acceleration     | m/s² | 4      | 3     | 3.5   | 6     | 3.5   | 5     | 4      | 3     |
| Gearbox Ratio        | -    | 3:1    | 4:1   | 3:1   | 3:1   | 3:1   | 3:1   | 3:1    | 3:1   |
| Motor Speed          | rpm  | 3,000  | 3,000 | 4,500 | 4,500 | 3,000 | 3,000 | 3,000  | 3,000 |
| Repeatable Precision | mm   |        |       |       |       |       |       |        | ±0.05 |

| Classification       | Unit             | CL - 1 |       |       |       | CL - 2 |       | CL - 3 |       |       |
|----------------------|------------------|--------|-------|-------|-------|--------|-------|--------|-------|-------|
| Classification       |                  | Xaxis  | Yaxis | Zaxis | Xaxis | Yaxis  | Zaxis | Xaxis  | Yaxis | Zaxis |
| Max Nominal Speed    | m/s              | 2.6    | 2.6   | 2.6   | 3     | 3      | 3     | 3.3    | 3.3   | 3.3   |
| Max Acceleration     | m/s <sup>2</sup> | 3.5    | 2     | 6     | 3.5   | 1      | 5     | 4      | 1     | 3     |
| Gearbox Ratio        | _                | 3:1    | 3:1   | 3:1   | 3:1   | 3:1    | 3:1   | 3:1    | 3:1   | 3:1   |
| Motor Speed          | rpm              | 4,500  | 4,500 | 4,500 | 3,000 | 3,000  | 3,000 | 3,000  | 3,000 | 3,000 |
| Repeatable Precision | mm               |        |       |       |       |        |       |        |       | ±0.05 |

## Track Motion Standard Type

## Overhead Type (TMS-O)

- > As a linear module that applied roller blocks and guide tracks for heavy weights, it moves industrial multi-joint robots in a straight direction to perform the role of expanding its area of work.
- > It is installed at the factory ceiling unlike the floor type to retain the existing strengths and the strengths of gantry robots. Can be used in a wider variety of fields.

| Maximum Effective Payload [kgf | Maximu | ım Effe | ctive I | Pavload | [kaf] |
|--------------------------------|--------|---------|---------|---------|-------|
|--------------------------------|--------|---------|---------|---------|-------|

| Туре     | 200 | 400 | 600 | 1,000 | 1,500 | 2,000 | 2,500 |
|----------|-----|-----|-----|-------|-------|-------|-------|
| TMS - 01 |     |     |     | 620   |       |       |       |
| TMS - 02 |     |     |     |       | 1,000 |       |       |
| TMS - 03 |     |     |     |       |       | 1,800 |       |





| Classification       | Unit | TMS - 01 |     |     |     | TMS - 02 |     | TMS - 03 |     |       |  |
|----------------------|------|----------|-----|-----|-----|----------|-----|----------|-----|-------|--|
| Max Nominal Speed    | m/s  | 3.3      | 2.5 | 1.6 | 3.3 | 2.2      | 1.6 | 2.6      | 2.2 | 1.6   |  |
| Max Acceleration     | m/s² | 8        | 7   | 6   | 4   | 3        | 2   | 4        | 3   | 2     |  |
| Gearbox Ratio        | _    | 3        | 4   | 6   | 4   | 6        | 8   | 5        | 6   | 8     |  |
| Motor Speed          | rpm  |          |     |     |     |          |     |          |     | 3,000 |  |
| Repeatable Precision | mm   |          |     |     |     |          |     |          |     | ±0.05 |  |

## Floor Type (TMS-F)

- > As a linear module that applied roller blocks and guide tracks for heavy weights, it moves industrial multi-joint robots in a straight direction to perform the role of expanding its area of work.
- Installed at the floor of the factory, it can perform various tasks such as product transport, assembly, welding, etc. in a wide using 1 robot.

#### Maximum Effective Payload [kgf]

| Туре     | 200 | 400 | 600 | 1,200 | 2,800 | 3,400 | 4,000 |
|----------|-----|-----|-----|-------|-------|-------|-------|
| TMS - F1 |     |     |     |       | 1,300 |       |       |
| TMS-F2   |     |     |     |       | 2,3   | 300   |       |
| TMS-F3   |     |     |     |       |       |       | 3,600 |





| Classification       | Unit | TMS - F1 |     |     |     | TMS - F2 |     | TMS-F3 |     |       |
|----------------------|------|----------|-----|-----|-----|----------|-----|--------|-----|-------|
| Max Nominal Speed    | m/s  | 3.3      | 2.5 | 1.8 | 3.3 | 2.2      | 1.6 | 2.6    | 2.2 | 1.6   |
| Max Acceleration     | m/s² | 8        | 7   | 6   | 8   | 7        | 6   | 4      | 3   | 2     |
| Gearbox Ratio        | -    | 3        | 4   | 6   | 4   | 6        | 8   | 5      | 6   | 8     |
| Motor Speed          | rpm  |          |     |     |     |          |     |        |     | 3,000 |
| Repeatable Precision | mm   |          |     |     |     |          |     |        |     | ±0.05 |

## **Customized Special Production**

In addition to standardized specifications based on payload capacity, customized specifications can be provided to meet customer requirements.



## **Gantry Robot Automation Solution**

## **Part Processing Line**





#### **Target Items**

Automative part and Other



#### **Products & Technologies Applied**

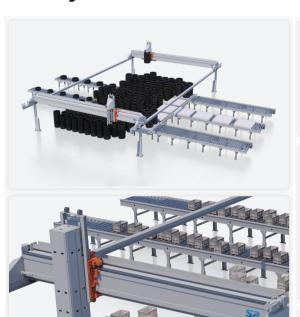
2-axis Gantry Robot, Dedicated gripper, Logistics automation system



**Applicable Fields** 

Entire industrial sectors utilizing machine tools

## **Gantry Robot Automated Warehouse**



#### **Target Items**

Tires, P-BOX, and Others



#### **Products & Technologies Applied**

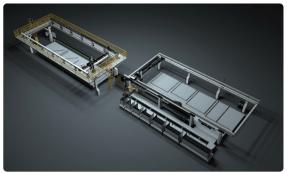
3-axis Gantry Robot, Dedicated gripper, Telescopic system, WCS(Warehouse Control System)



**Applicable Fields** 

Comprehensive logistics for flat-stacked items, such as tires and square boxes.

## **Precast Concrete Manufacturing Automation**



#### **Target Items**

Shutters for PC manufacturing



#### **Products & Technologies Applied**

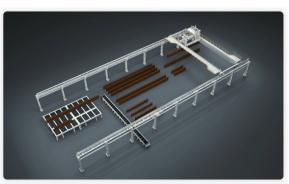
3-axis Gantry Robot, Dedicated gripper, Drawing information conversion system



**Applicable Fields** 

Precast concrete panel manufacturing sector

## **Heavy-Duty Automated Transfer**





#### **Target Items**

Large construction materials and Other heavy meterials



## **Products &**

### **Technologies Applied**

Multi-axis (4 or more) Gantry Robot, Dedicated gripper, Structural design technology for handling heavy loads from 1 ton to 10 tons

**Applicable Fields** 

Industrial sectors requiring transportation of heavy loads over 1 ton

## **Automated Logistics Warehouse**



#### **Target Items**

Pallet cargo, BOX cargo, and Others





#### **Products &**

#### **Technologies Applied**

Shuttle robots, Stacker cranes, WCS (Warehouse Control System solution)

Applicable Fields

Storage and input/output management of pallet and box cargo across all industries

# **Automated Logistics for 2nd Battery Component Manufacturing**



#### **Target Items**

Secondary battery cans and CAP Assy



## Products & Technologies Applied

Rivet assembly automation, Vision inspection, Helium leak inspection, Palletizing, Logistics automation

Applicable Fields

High-speed small component manufacturing lines in all industries (60 PPM or higher)

## **Major Customers**



## **Global Expansion**







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